

Surface Stereo with Soft Segmentation

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Dense Stereo Matching



(Left Image)

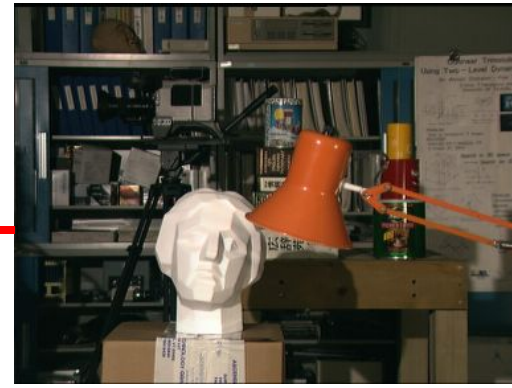


(Right Image)

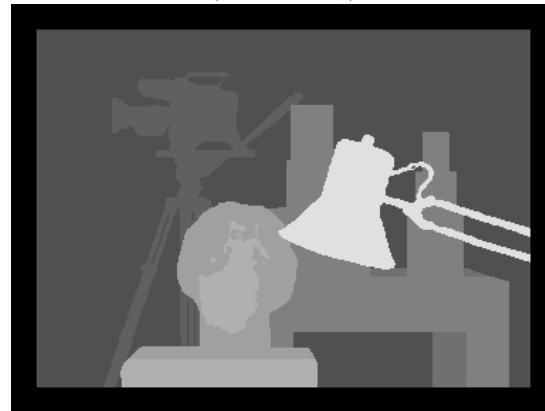
Dense Stereo Matching



(Left Image)



(Right Image)



(Disparity Map)

Common Approaches



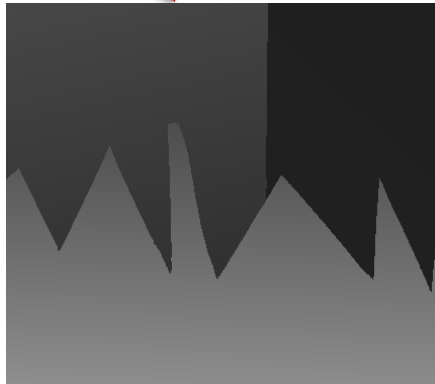
Reference image

Common Approaches

Assign pixels to
disparity values



Reference image



Disparity map

Our Approach



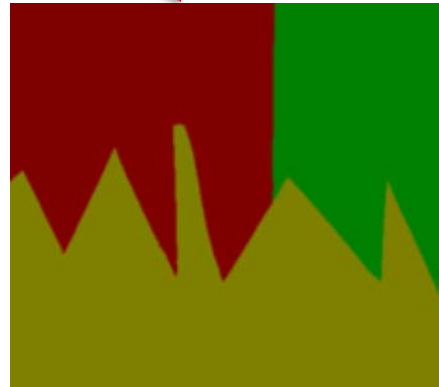
Reference image

Our Approach

Assign pixels
to 3D surfaces



Reference image



Surface map

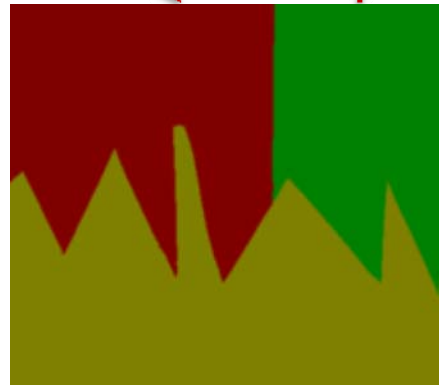
Our Approach

Assign pixels
to 3D surfaces

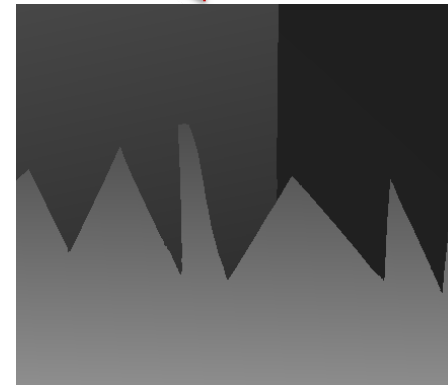
Surfaces implicitly
define disparities



Reference image



Surface map



Disparity map

Our Approach

Assign pixels
to 2D surfaces

Surfaces implicitly
define disparities

- Our approach simultaneously infers:
 1. Which surfaces are present in the scene
 2. Which pixels belong to which surface



Reference image



Surface map



Disparity map

Energy

- Search an assignment of pixels to surfaces that minimizes an energy:

Data Term:

Computes pixel dissimilarities;
Penalty for occluded pixels

Smoothness Term:

Penalty on spatially neighboring pixels assigned to different surfaces

Soft Segmentation Term:

Penalty on inconsistencies with a given color segmentation

MDL Term:

Penalty on the number of surfaces

Curvature Term:

Penalty on disparity curvature

- Surfaces: planes or B-splines.

Energy

- Search and optimization algorithms to surfaces that minimizes an energy:

Contributions



Data Term:

Computes pixel dissimilarities;
Penalty for occluded pixels

Smoothness Term:

Penalty on spatially neighboring pixels assigned to different surfaces

Soft Segmentation Term:

Penalty on inconsistencies with a given color segmentation

MDL Term:

Penalty on the number of surfaces

Curvature Term:

Penalty on disparity curvature

- Surfaces: planes or B-splines.

Soft Segmentation Term

- Common segmentation-based methods:
 - Color segmentation of reference image
 - Assign each segment to a single surface
 - Fail if segment overlaps a disparity discontinuity.



Map reference image



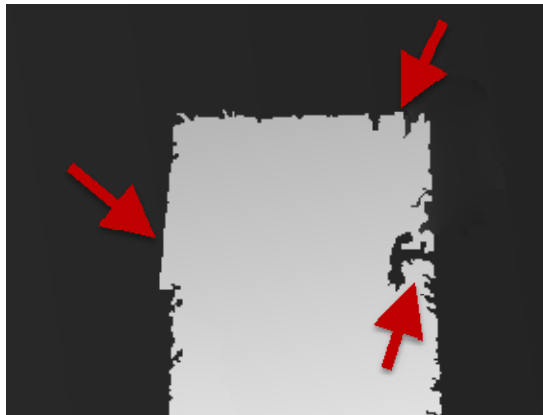
Ground truth disparities



Result of hard segmentation method

Soft Segmentation Term

- Our approach:
 - Prefer solutions consistent with a segmentation (lower energy).
 - Segmentation = soft constraint.

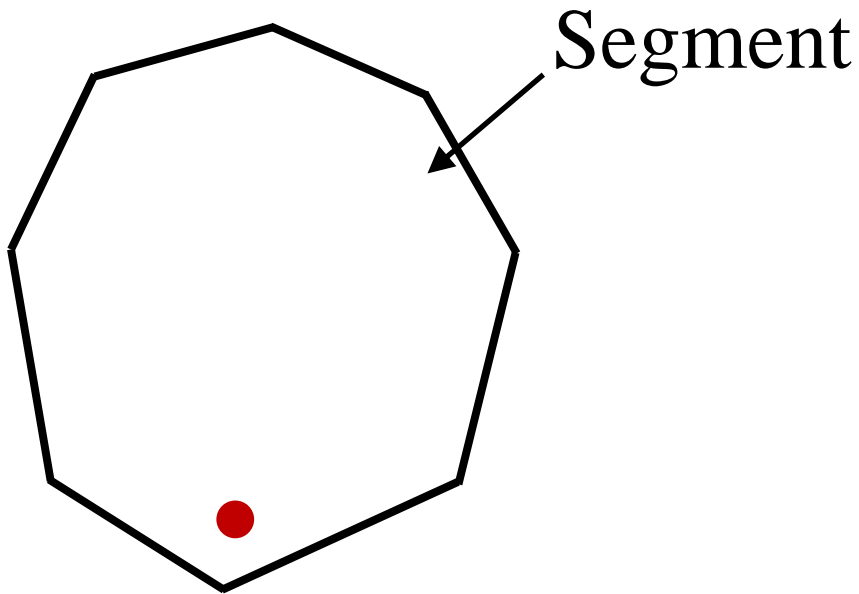


Result of hard
segmentation method

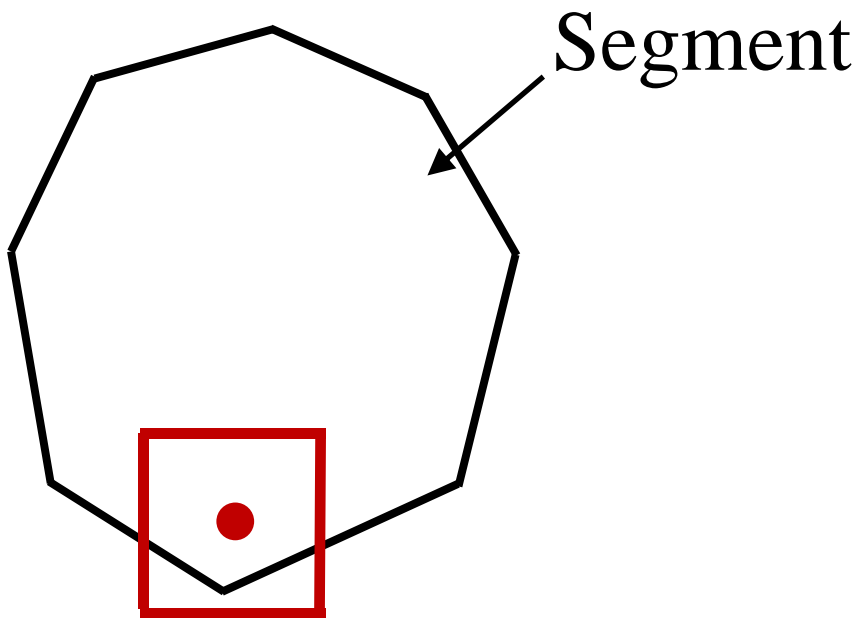


Our result

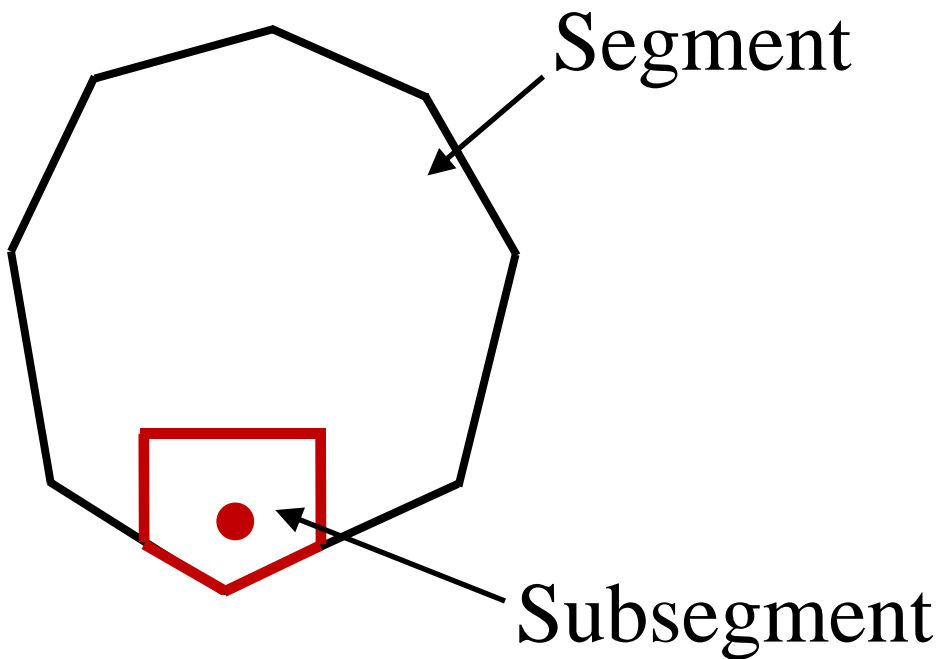
Soft Segmentation Term



Soft Segmentation Term

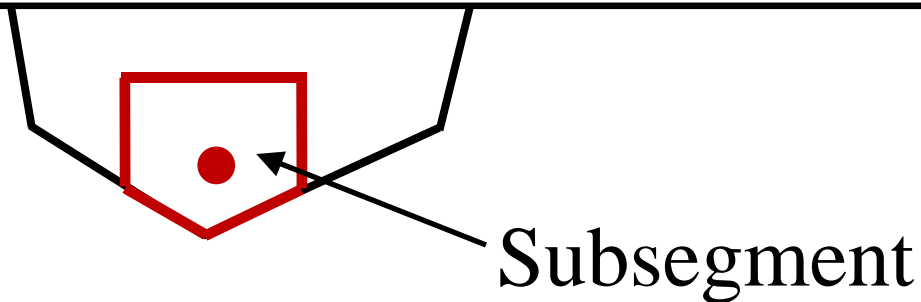


Soft Segmentation Term

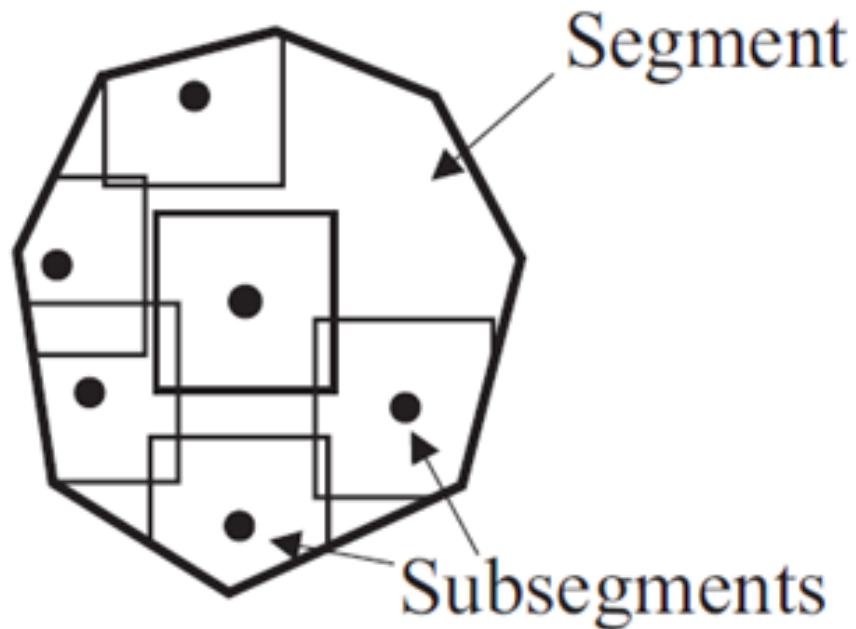


Soft Segmentation Term

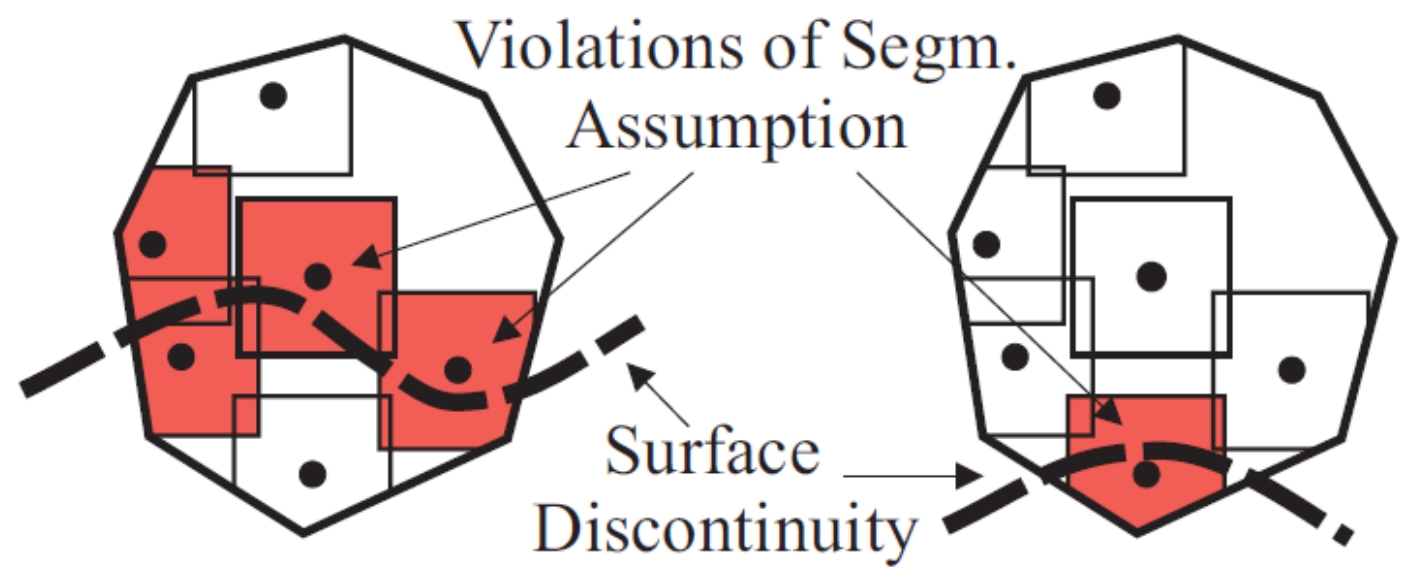
- Our term:
 - 0 penalty if all pixels within subsegment assigned to the same **surface**
 - Constant penalty, otherwise



Soft Segmentation Term



Soft Segmentation Term

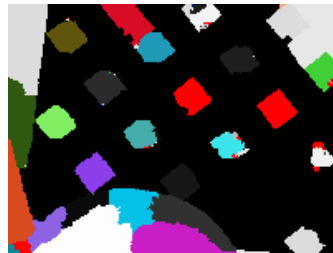


MDL Term

- Simple scene explanation better than unnecessarily complex one.
- Penalty on the number of surfaces.
- Solution containing 5 surfaces cheaper than one with 100 surfaces.



Crop of the
Cones image



Solution without our MDL term.



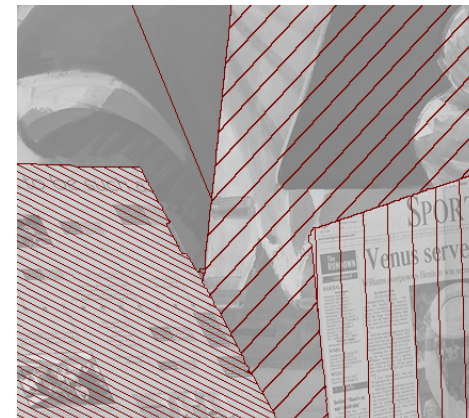
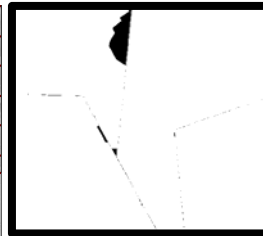
Our MDL term.

Curvature Term

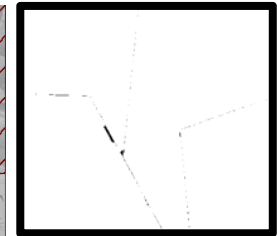
- Second order priors:
 - Difficult to optimize in disparity-based representation due to triple cliques [Woodford et al., CVPR08].
- Our approach:
 - Curvature analytically computed from surface model.
 - Easy to optimize in surface-based representation (unary term).



Result without curvature term.

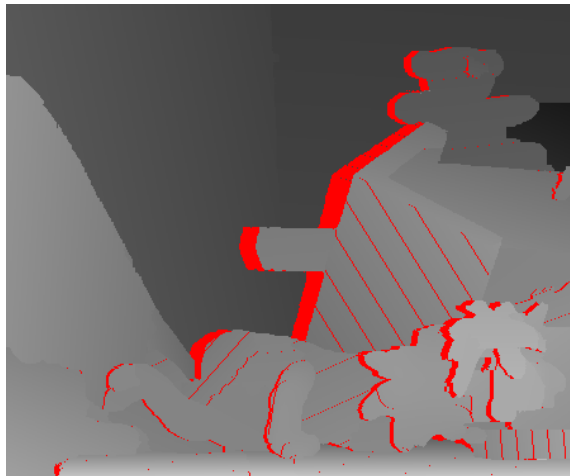


Result with curvature term.

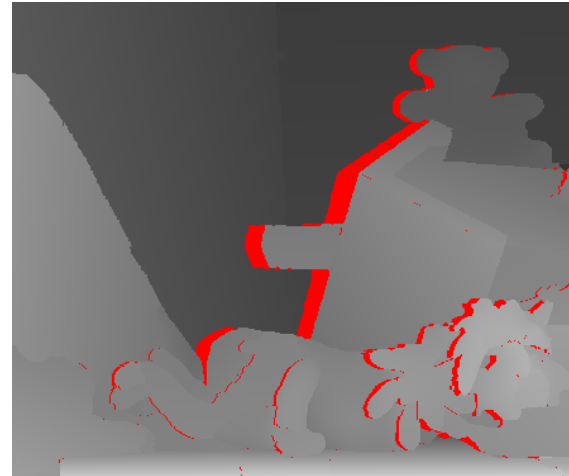


Improved Asymmetric Occlusion Handling

- Uniqueness assumption violated for slanted surfaces:
 - Several pixels of the same surface correspond to a single pixel of the second view.
- Our approach:
 - Pixels must not occlude each other if they lie on same surface.
 - Avoids wrongly detected occlusions at slanted surfaces.



Standard Occlusion Handling

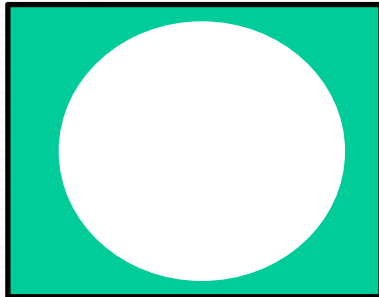


Ours

Energy Optimization

- Not easy – label set of infinite size!
- Fusion move approach [Lempitsky et al., ICCV07]:

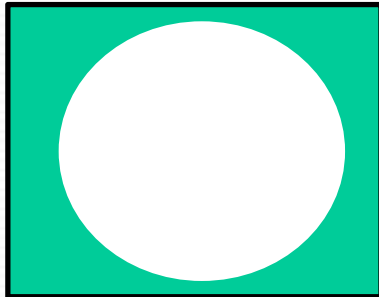
Current Solution



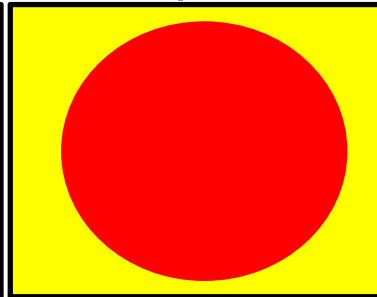
Energy Optimization

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Current Solution

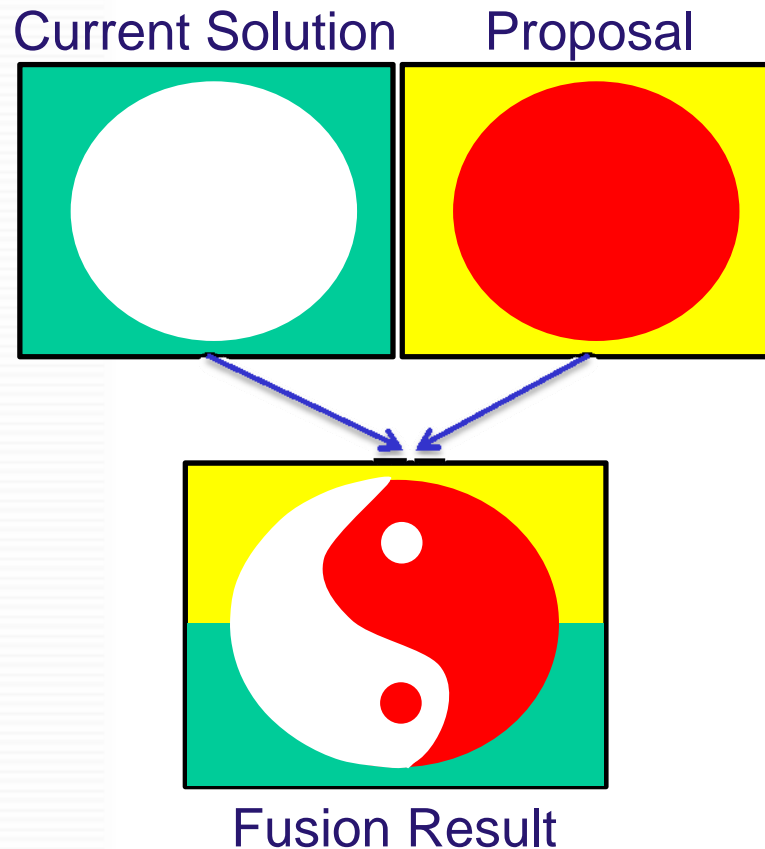


Proposal



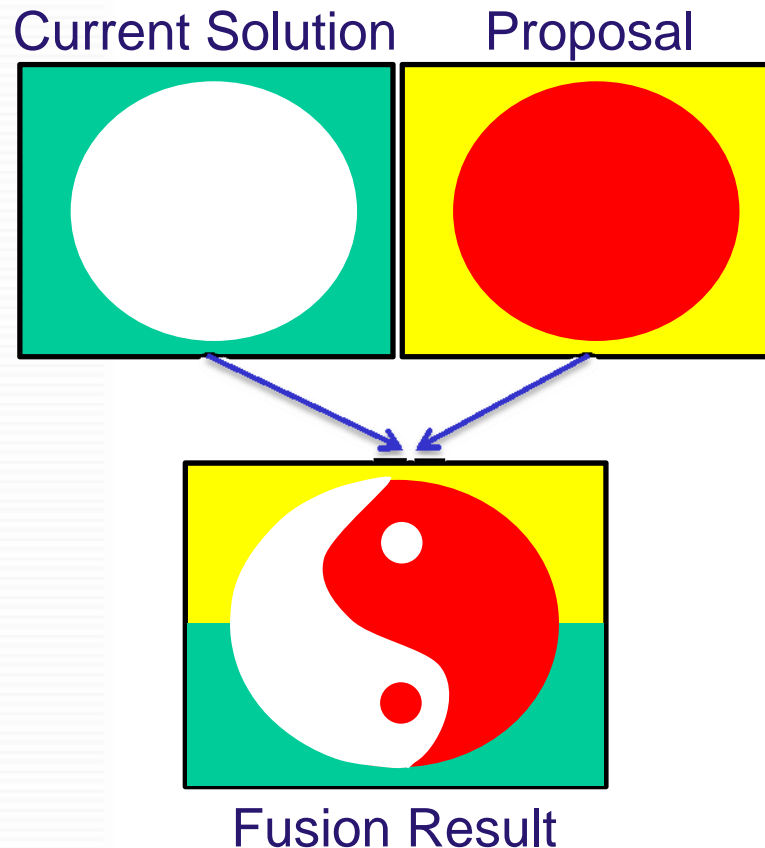
Energy Optimization

- Not easy – label set of infinite size!
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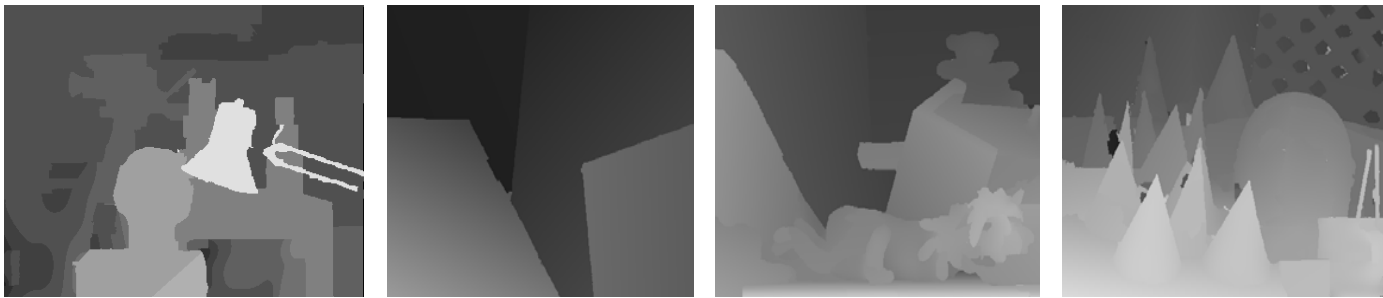


Energy Optimization

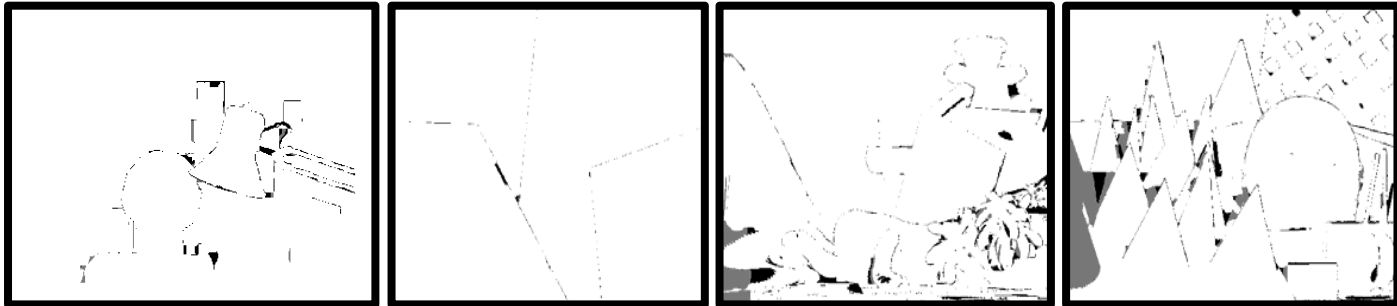
- Not easy – label set of infinite size!
- Fusion move approach [Lempitsky et al., ICCV07]:



- Computing the “optimal” fusion move:
 - Recent work on sparse higher-order cliques ([Kohli et al., CVPR07] and [Rother et al., CVPR09]) for implementing soft segmentation term.
 - Non-submodular energy optimized via QPBOI.



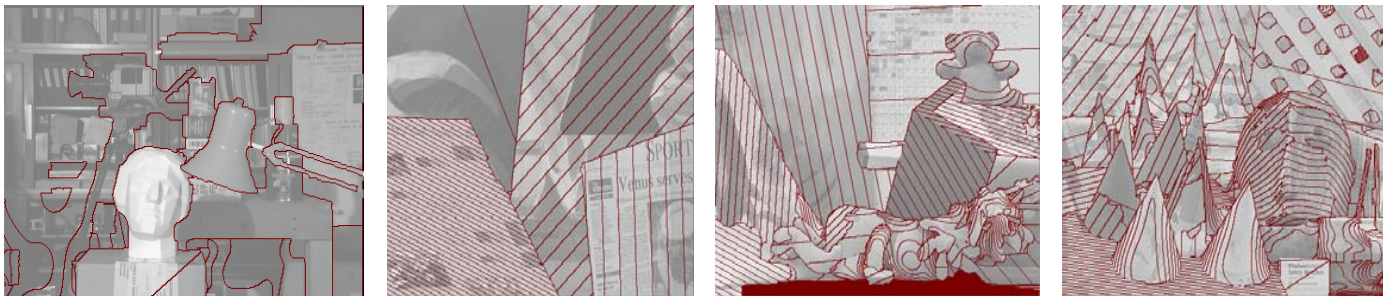
Computed disparity maps



Disparity errors > 1 pixel



Assignment of pixels to surfaces



Left images with contour lines overlaid

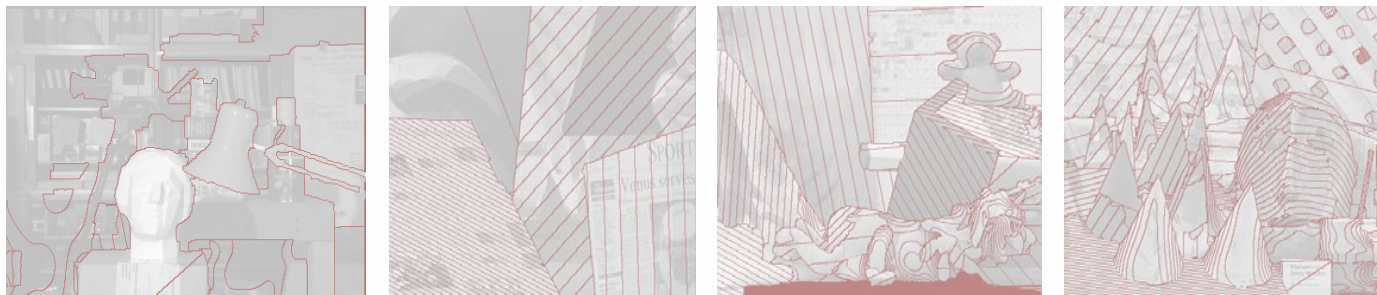


Computed disparity maps

- 6th rank out of ~90 submissions in the Middlebury online table.
- 1th rank for the complex Teddy set on all error measures.



Assignment of pixels to surfaces



Left images with contour lines overlaid



Conclusions

- Surface-based representation is important.
- Enables several important contributions:
 - Soft segmentation
 - MDL prior